

# Smallest Eigenvalue of M-Matrices

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- Def: M-Matrix

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{bmatrix}; \quad \begin{array}{l} a_{ii} \geq 0 \\ a_{ij} \leq 0, \quad i \neq j \\ \text{Row Sums } s_i = \sum_{j=1}^n a_{ij} \geq 0 \end{array}$$

- Given: Row sums  $s_i$  and off diagonals  $a_{ij}, i \neq j$ .
- Diagonal elements computable accurately, sum of positives

$$a_{ii} = s_i - \sum_{j \neq i} a_{ij}$$

# GE on Weakly Diagonally Dominant M-Matrices

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- Pivoting, if needed, is diagonal, preserves structure
- One step of GE:
  - Off diagonals:  $a_{ij} = a_{ij} - \frac{a_{ik}a_{kj}}{a_{kk}}$
  - Row sums:  $s_i = s_i - \frac{a_{ik}}{a_{kk}}s_k$
- Everything is preserved in Schur complementation
  - Weak diagonal dominance
  - M-matrix structure
  - High relative accuracy in  $a_{ij}$  and  $s_i$
- Yields Cholesky factors

## Getting the inverse

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- Again no subtractions in solving

$$\begin{bmatrix} c_{11} & c_{12} & c_{13} & c_{14} \\ & c_{22} & c_{23} & c_{24} \\ & & c_{33} & c_{44} \\ & & & c_{44} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$$

- Think of  $b$  as  $e_i$  or  $> 0$  in general.

$$x_4 = b_4 / c_{44}$$

$$x_3 = (b_3 - c_{34}x_4) / c_{33}$$

$$x_2 = (b_2 - c_{24}x_4 - c_{23}x_3) / c_{22}$$

$$x_1 = (b_1 - c_{14}x_4 - c_{13}x_3 - c_{12}x_2) / c_{11}$$

- Solving with  $C^T$  analogous  $\Rightarrow A^{-1}$  – positive.
- Accurate (Positive) Inverse = Accurate smallest eigenvalue (even in the nonsymmetric case)