## 5 Homework Solutions

### 18.335 - Fall 2004

### 5.1 Trefethen 20.1

$\Rightarrow$ If $A$ has an LU factorization, then all diagonal elements of $U$ are not zero. Since $A=L U$ implies that $A_{1: k, 1: k}=L_{1: k, 1: k} U_{1: k, 1: k}$ we get that $A_{1: k, 1: k}$ is invertible.
$\Leftarrow$ We prove by induction that $A_{1: k, 1: k}=L_{1: k, 1: k} U_{1: k, 1: k}$ with

$$
L_{1: k+1,1: k+1}=\left(\begin{array}{cc}
L_{1: k, 1: k} & 0 \\
* * * & 1
\end{array}\right) \text { and } U_{1: k+1,1: k+1}=\left(\begin{array}{cc}
U_{1: k, 1: k} & * \\
0 & u_{k+1}
\end{array}\right)
$$

with all the elements on the diagonal of $U_{1: k, 1: k}$ are non-zero for any $k$.
Step 1 For $k=1$ we have $A_{1: 1,1: 1}=L_{1: 1,1: 1} U_{1: 1,1: 1}$ with $L_{1: 1,1: 1}=1, U_{1: 1,1: 1}=$ $\bar{A}_{1: 1,1: 1} \neq 0$.

Step 2 If that is true for $k \leq m$ we prove it for $m+1$. Simply choose:

$$
A_{1: m+1,1: m+1}=\underbrace{\left(\begin{array}{cc}
L_{1: m, 1: m} & 0 \\
X_{m} & 1
\end{array}\right)}_{L_{1: m+1,1: m+1}} \underbrace{\left(\begin{array}{cc}
U_{1: m, 1: m} & Y_{m} \\
0 & u_{m+1}
\end{array}\right)}_{U_{1: m+1,1: m+1}}
$$

with

$$
\begin{aligned}
X_{m} & =\left[a_{m+1,1} \ldots a_{m+1, m}\right] U_{1: m, 1: m}^{-1} \\
Y_{m} & =L_{1: m, 1: m}^{-1}\left[\begin{array}{c}
a_{1, m+1} \\
\vdots \\
a_{m, m+1}
\end{array}\right] \\
u_{m+1} & =-X_{m} Y_{m}
\end{aligned}
$$

Now we have $u_{m+1} \neq 0$ since $\operatorname{det}\left(A_{1: m+1,1: m+1}\right)=\operatorname{det}\left(U_{1: m, 1: m}\right) u_{m+1} \neq$ 0 . Now since $A=A_{1: n, 1: n}=L_{1: n, 1: n} U_{1: n, 1: n}$ and $L_{1: n, 1: n}$ is unit lower diagonal, $U_{1: n, 1: n}$ is upper diagonal and we complete the proof.

### 5.2 Trefethen 21.6

Write

$$
A=\left(\begin{array}{ll}
a_{11} & A_{12} \\
A_{21} & A_{22}
\end{array}\right)
$$

Proceed with the first step of Gaussian elimination:

$$
\left(\begin{array}{cc}
a_{11} & A_{12} \\
0 & A_{22}-\frac{A_{21}}{a_{11}} A_{12}
\end{array}\right)
$$

Now for $A_{22}-\frac{A_{21}}{a_{11}} A_{12}$ we show that it has the property of strictly diagonally dominant matrices.

$$
\sum_{j \neq k}\left|\left(A_{22}-\frac{A_{21}}{a_{11}} A_{12}\right)_{j k}\right| \leq \sum_{j \neq k}\left|\left(A_{22}\right)_{j k}\right|+\sum_{j \neq k}\left|\frac{1}{a_{11}}\left(A_{21}\right)_{j}\left(A_{12}\right)_{k}\right|
$$

$A$ is strictly diagonally dominant, so we may write

$$
\sum_{j \neq k}\left|\left(A_{22}\right)_{j k}\right|<\left|\left(A_{22}\right)_{k k}\right|-\left|\left(A_{12}\right)_{k}\right| \text { and } \sum_{j \neq k}\left|\left(A_{21}\right)_{j}\right|<\left|a_{11}\right|-\left|\left(A_{21}\right)_{k}\right|
$$

so that in the end we get:

$$
\begin{aligned}
\sum_{j \neq k}\left|\left(A_{22}-\frac{A_{21}}{a_{11}} A_{12}\right)_{j k}\right| & <\left|\left(A_{22}\right)_{k k}\right|-\left|\left(A_{12}\right)_{k}\right|+\frac{\left|\left(A_{12}\right)_{k}\right|}{\left|a_{11}\right|}\left(\left|a_{11}\right|-\left|\left(A_{21}\right)_{k}\right|\right) \\
& <\left|\left(A_{22}\right)_{k k}\right|-\frac{\left|\left(A_{12}\right)_{k}\right|\left|\left(A_{21}\right)_{k}\right|}{\left|a_{11}\right|} \leq\left|\left(A_{22}\right)_{k k}-\frac{\left(A_{21}\right)_{k}\left(A_{12}\right)_{k}}{a_{11}}\right| \\
& \leq\left|\left(A_{22}-\frac{A_{21} A_{12}}{a_{11}}\right)_{k k}\right|
\end{aligned}
$$

Hence by induction if the property is true for any matrix of dimension $\leq m-1$ then it is true for any matrix $A$ of $\operatorname{dim} A=n$. This means that the submatrices that are created by successive steps of Gaussian elimination are also strictly diagonally dominant and hence we have no need for row swappings.

### 5.3 Trefethen 22.1

Apply 1 step of Gaussian elimination to $A$ :

$$
\left(\begin{array}{cccc}
a_{11} & a_{12} & \cdots & a_{1 m} \\
a_{21} & a_{22} & \cdots & a_{2 m} \\
\vdots & \vdots & \ddots & \vdots \\
a_{m 1} & a_{m 2} & \cdots & a_{m m}
\end{array}\right) \xrightarrow[\text { of GE }]{1 \text { Step }}\left(\begin{array}{cccc}
a_{11} & a_{12} & \cdots & a_{1 m} \\
0 & a_{22}^{(1)} & \cdots & a_{2 m}^{(1)} \\
\vdots & \vdots & \ddots & \vdots \\
0 & a_{m 2}^{(1)} & \cdots & a_{m m}^{(1)}
\end{array}\right)
$$

, where the entries $a_{i j}^{(1)}=a_{i j}-l_{i k} a_{k j}$. Since we used partial pivoting in our calculation, we must have $\left|l_{i k}\right| \leq 1$,

$$
\left|\tilde{a}_{i j}\right|=\left|a_{i j}-l_{i k} a_{k j}\right| \leq\left|a_{i j}\right|+\left|l_{i k}\right|\left|a_{k j}\right| \leq\left|a_{i j}\right|+\left|a_{k j}\right| \leq 2 \max _{i, j}\left|a_{i, j}\right|
$$

In order to form $A$ we need $m-1$ such steps, so in the end we have:

$$
\left|u_{i j}\right| \leq 2 \max _{i, j}\left|a_{i, j}^{(m-2)}\right| \leq 2 \max _{i, j}\left|a_{i, j}^{(m-3)}\right| \leq \ldots \leq 2 \max _{i, j}\left|a_{i, j}\right|
$$

so that we obtain $\left|u_{i j}\right| \leq 2^{m-1} \max _{i, j}\left|a_{i, j}\right|$. Therefore

$$
\rho=\frac{\max _{i, j}\left|u_{i, j}\right|}{\max _{i, j}\left|a_{i, j}\right|} \leq 2^{m-1}
$$

5.4 Let $A$ be symmetric and positive definite. Show that $\left|a_{i j}\right|^{2}<a_{i i}$ $a_{j j}$.
Since $A$ is symmetric and positive definite, it has all $a_{i i}$ positive and for any vector $x$ we have $x^{T} A x>0$. Choose $x$ such that $x_{k}=\delta_{j k} a_{j j}-\delta_{i k} a_{i j}$, where $\delta_{l m}$ is the Kronecker delta, meaning that all the entries of $x$ are zero except the $i$-th and the $j$-th entries which equal to $-a_{i j}$ and $a_{j j}$ respectively . Carrying out the calculation gives $x^{T} A x=a_{i i}\left(a_{i i} a_{j j}-a_{i j}^{2}\right)>0$ thus completing the proof.
5.5 Let $A$ and $A^{-1}$ be given real $n$-by- $n$ matrices. Let $B=A+x y^{T}$ be a rank-one perturbation of $A$. Find an $O\left(n^{2}\right)$ algorithm for computing $B^{-1}$. Hint: $B^{-1}$ is a rank-one perturbation of $A^{-1}$.

Since $B^{-1}$ is a rank-one perturbation of $A^{-1}$ we may write $B^{-1}=A^{-1}+u v^{T}$. Then

$$
\begin{aligned}
B B^{-1} & =\left(A+x y^{T}\right)\left(A^{-1}+u v^{T}\right) \\
I & =I+A u v^{T}+x y^{T} A^{-1}+x y^{T} u v^{T} \\
0 & =A u v^{T}+x y^{T} A^{-1}+x y^{T} u v^{T}
\end{aligned}
$$

Choosing $u=A^{-1} x$, allows us to write:

$$
\begin{aligned}
0 & =x v^{T}+x y^{T} A^{-1}+x y^{T} u v^{T} \\
0 & =v^{T}+y^{T} A^{-1}+y^{T} u v^{T} \\
0 & =v^{T}\left(1+y^{T} u\right)+y^{T} A^{-1} \\
v^{T} & =-\frac{y^{T} A^{-1}}{1+y^{T} A^{-1} x}
\end{aligned}
$$

Hence $B^{-1}$ is given by:

$$
B^{-1}=A^{-1}-\frac{A^{-1} x y^{T} A^{-1}}{1+y^{T} A^{-1} x}
$$

It is easy to see that the inverse can be computed in $O\left(n^{2}\right)$ operations

