

GMS systems

Haynes Miller, summer 2002

This is a workup of the algebraic structure called a “vertex algebroid” by Gorbounov, Malikov, and Schechtman [2] and Bressler [1].

Definition. A Palais algebra over a commutative ring k is a commutative k -algebra A and a Lie algebra T over k together with k -linear maps $A \otimes T \rightarrow T$ and $T \otimes A \rightarrow A$ which establish T as an A -module and A as a T -module and which satisfy

$$s(bc) = (sa)b + a(sb), \quad [s, bt] = (sb)t + b[s, t],$$

for $a, b, c \in A$ and $s, t \in T$.

A module over a Palais algebra (A, T) is a k -module M together with k linear maps $A \otimes M \rightarrow M$ and $T \otimes M \rightarrow M$ which establish M as an A -module and as a T -module and which satisfy

$$s(ax) = (sa)x + a(sx)$$

for $s \in T$, $a \in A$, $x \in M$.

The characteristic example is given by taking any commutative k -algebra A and letting $T = \text{Der}_k(A, A)$ with its obvious structures as Lie algebra of operators by derivations on A and as left A -module.

The A -module of Kähler differentials $\Omega_{A/k}$ forms the characteristic example of an (A, T) -module, with $T = \text{Der}_k(A, A)$. The T -module structure $T \otimes \Omega_{A/k} \rightarrow \Omega_{A/k}$ is given by the “Lie derivative,” characterized by the equation

$$t(a \partial b) = (ta) \partial b + a \partial (tb).$$

To verify that this map is well defined one can use the fact that the module of Kähler differentials is given by dividing the free A -module generated by the set A (in which an element $a \in A$ of the generating set is written as ∂a) by the relations

$$\partial(ab) = a \partial b + b \partial a, \quad \partial k = 0.$$

In fact, this example has two additional bits of structure: (1) the universal derivation $\partial : A \rightarrow \Omega_{A/k}$; and (2) an A -bilinear pairing

$$T \otimes \Omega_{A/k} \rightarrow A,$$

defined as the adjoint of the canonical isomorphism $T \cong \text{Hom}_A(\Omega_{A/k}, A)$, or by the formula

$$\langle t, b \partial c \rangle = b(tc).$$

This gives us the following structure.

Definition. A pre-GMS algebra over a commutative ring k consists in a Palais algebra (A, T) and a module Ω for it, together with a map $\partial : A \rightarrow \Omega$ of T -modules and an A -bilinear pairing $\langle -, - \rangle : T \otimes \Omega \rightarrow A$ satisfying the identities

$$\begin{aligned} \langle t, \partial b \rangle &= tb \\ (at)\omega &= a(t\omega) + \langle t, \omega \rangle \partial a \\ s\langle t, \omega \rangle &= \langle [s, t], \omega \rangle + \langle t, s\omega \rangle. \end{aligned}$$

We now come to the main definition.

Definition. A GMS algebra over a commutative ring k consists of k -modules A and V together with an element $1 \in A$ and k -linear maps

$$\begin{aligned} \partial : A &\rightarrow V, \quad A \otimes A \rightarrow A, \\ \cdot : A \otimes V &\rightarrow V, \quad \langle -, - \rangle : V \otimes V \rightarrow A, \quad [-, -] : V \otimes V \rightarrow V \end{aligned}$$

subject to the following axioms.

$$1a = a, \quad a(bc) = (ab)c, \quad ab = ba,$$

so A forms a commutative k -algebra with unit 1; and

$$\begin{aligned} 1 \cdot x &= x, \quad \langle x, y \rangle = \langle y, x \rangle \\ a \cdot (b \cdot z) &= (ab) \cdot z + \langle \partial b, z \rangle \cdot \partial a + \langle \partial a, z \rangle \cdot \partial b \\ \partial(ab) &= a \cdot \partial b + b \cdot \partial a, \quad [x, y] + [y, x] = \partial \langle x, y \rangle \\ \langle \partial a, \partial b \rangle &= 0, \quad [\partial a, y] = 0 \\ [x, b \cdot z] &= b \cdot [x, z] + \langle x, \partial b \rangle \cdot z \\ [[x, y], z] &= [x, [y, z]] - [y, [x, z]] \\ \langle a \cdot y, z \rangle &= a \langle y, z \rangle - \langle y, [z, \partial a] \rangle \\ \langle [x, y], z \rangle + \langle [x, z], y \rangle &= \langle x, \partial \langle y, z \rangle \rangle. \end{aligned}$$

The structure given by GMS includes three further structure maps, which are given in terms of our choice of primitive operations by

$$A \otimes V \rightarrow A \quad \text{by} \quad a \otimes y \mapsto -\langle \partial a, y \rangle$$

$$V \otimes A \rightarrow A \quad \text{by} \quad x \otimes b \mapsto \langle x, \partial b \rangle$$

$$V \otimes A \rightarrow V \quad \text{by} \quad x \otimes b \mapsto b \cdot x + [x, \partial b].$$

We will give the second of these operations a notation:

$$xb = \langle x, \partial b \rangle.$$

Then it's easy to check the equations

$$\partial(xb) = [x, \partial b],$$

$$x(bc) = b \cdot (xc) + c \cdot (xb),$$

$$[x, y]c = x(yc) - y(xc),$$

$$[x, b \cdot z] = b \cdot [x, z] + (xb) \cdot z.$$

It is also useful to note the equation

$$[a \cdot \partial b, z] = \langle \partial b, z \rangle \cdot \partial a - \langle \partial a, z \rangle \cdot \partial b.$$

Let Ω denote the sub k module of V generated by the elements $a \cdot \partial b$ as a and b run over A . Then it is easy and fun to check the following statements. The operation \cdot defines an A -module structure on Ω , the operation $[-, -]$ defines a Lie algebra structure on the k -module quotient $T = V/\Omega$, and the operation $x, b \mapsto xb$ defines a T -module structure on A , in such a way that (A, T) forms a Palais algebra. Moreover, the operation $[-, -]$ defines a T -module structure on Ω in such a way that Ω becomes a module for this Palais algebra. For the last one checks that the bracket of two elements of Ω is trivial.

The Palais algebra structure underlies a natural GMS algebra structure, in which $\partial : A \rightarrow \Omega$ is the corestriction of $\partial A \rightarrow V$ and the pairing $\langle -, - \rangle : T \otimes \Omega \rightarrow A$ descends from the pairing on V . For the last, one checks that $\Omega \subset V$ is self-orthogonal with respect to the pairing.

This work defines the functor in the

Proposition. A GMS algebra has an underlying pre-GMS algebra.

Let (A, V) be GMS algebra, and assume that the map $V \rightarrow T$ has a k -linear section. Use this section to express

$$V = \Omega \oplus T$$

and the structure maps accordingly. We will use this decomposition to describe what information must be added to the pre-GMS system in order to specify the GMS system. We will simply identify T with its image in V .

For $a \in A$, $a \cdot$ induces actions on Ω and on T , but may have a component sending T into Ω : so we need to give a map

$$\alpha : A \otimes T \rightarrow \Omega.$$

In terms of it,

$$a \cdot \begin{pmatrix} \omega \\ t \end{pmatrix} = \begin{pmatrix} a\omega + \alpha(a, t) \\ at \end{pmatrix}.$$

The pairing $\langle -, - \rangle$ is symmetric, Ω is self-orthogonal, and we are given the induced pairing $T \otimes \Omega \rightarrow A$, so what remains to specify is the restriction of the pairing to T in V : a map

$$\gamma : T \otimes T \rightarrow A.$$

In terms of it,

$$\left\langle \begin{pmatrix} \zeta \\ s \end{pmatrix}, \begin{pmatrix} \omega \\ t \end{pmatrix} \right\rangle = \langle s, \omega \rangle + \langle t, \zeta \rangle + \gamma(s, t).$$

Finally, the bracket $[-, -]$ takes the form

$$\left[\begin{pmatrix} \zeta \\ s \end{pmatrix}, \begin{pmatrix} \omega \\ t \end{pmatrix} \right] = \begin{pmatrix} \partial \langle t, \zeta \rangle - t\zeta + s\omega + \beta(s, t) \\ [s, t] \end{pmatrix}$$

where

$$\beta : T \otimes T \rightarrow \Omega.$$

These three maps satisfy various relations:

$$\alpha(1, t) = 0, \quad \gamma(s, t) = \gamma(t, s),$$

$$\begin{aligned}
\alpha(a, bt) - \alpha(ab, t) + a\alpha(b, t) &= (tb) \partial a + (ta) \partial b \\
\partial \gamma(s, t) &= \beta(s, t) + \beta(t, s) \\
\alpha(sb, t) - s\alpha(b, t) + \alpha(b, [s, t]) &= \beta(s, bt) - b\beta(s, t). \\
s\beta(t, u) - t\beta(s, u) + u\beta(s, t) - \beta([s, t], u) &+ \beta(s, [t, u]) - \beta(t, [s, u]) = \partial \langle u, \beta(s, t) \rangle. \\
a\gamma(s, t) - \gamma(as, t) &= \langle t, \alpha(a, s) \rangle + [s, t]a \\
s\gamma(t, u) &= \langle u, \beta(s, t) \rangle + \gamma([s, t], u) + \langle t, \beta(s, u) \rangle + \gamma([s, u], t).
\end{aligned}$$

One can change the splitting by means of a k -linear map $f : T \rightarrow \Omega$, replacing $t \in V$ with $t + f(t)$. The effect on the three maps is given by

$$\begin{aligned}
(f \cdot \alpha)(a, t) &= \alpha(a, t) + af(t) \\
(f \cdot \beta)(s, t) &= \beta(s, t) + \partial \langle t, f(s) \rangle - tf(s) + sf(t) \\
(f \cdot \gamma)(s, t) &= \gamma(s, t) + \langle s, f(t) \rangle + \langle t, f(s) \rangle.
\end{aligned}$$

References

- [1] Paul Bressler, Vertex Algebroids I, <https://arxiv.org/abs/math/0202185>
- [2] Vassily Gorbounov, Fyodor Malikov, and Vadim Schechtman, Gerbes of chiral differential operators. II. Vertex algebroids. *Invent. Math.* 155 (2004) 605680.