

# Design and Analysis of Optimal Filters

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The classical problem of lowpass filter design begins with a passband  $|\omega| \leq \omega_p$  and a stopband  $\omega_s \leq |\omega| \leq \pi$ . We look for the trigonometric polynomial of degree  $2N + 1$  that best approximates 1 on the passband and 0 on the stopband. If the maximum error is  $\delta$ , then the error over these intervals oscillates with equal ripples of size  $\delta$ . The Remez algorithm produces the optimal polynomial.

We study three basic questions about this polynomial:

1. The asymptotic value of  $\delta$  has the form  $c N^{-1/2} \exp(-N\beta)$   
We determine the value of  $\beta$ . This improves an empirical formula that is frequently used to choose the correct degree  $N$  for given  $\delta$ .
2. We determine the leading term in the asymptotic form of the polynomial in the transition band  $\omega_p < |\omega| < \omega_s$ . It approaches an error function (confirmed numerically).
3. We propose a faster algorithm based on interpolation at rescaled Chebyshev points, to give an approximately optimal filter design.

The basic technique is analysis of the Green's function for a doubly connected region in the complex plane (the complement of two intervals). We rely on stationary phase for asymptotic estimates.